

# Operating Systems: Lecture 8

## Synchronization Examples

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## *Chapter 7: Synchronization Examples*

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- Classic Problems of Synchronization
- Synchronization within the Kernel
- POSIX Synchronization
- Synchronization in Java
- Alternative Approaches

## *Classical Problems of Synchronization*

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- Classical problems used to test newly-proposed synchronization schemes
  - Bounded-Buffer Problem
  - Readers and Writers Problem
  - Dining-Philosophers Problem

## *Bounded-Buffer Problem*

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- $n$  buffers, each can hold one item
- Semaphore `mutex` initialized to the value 1
- Semaphore `full` initialized to the value 0
- Semaphore `empty` initialized to the value  $n$

- The structure of the *producer* process

```
do {  
    ...  
    /* produce an item in next_produced */  
    ...  
    wait(empty);  
    wait(mutex);  
    ...  
    /* add next produced to the buffer */  
    ...  
    signal(mutex);  
    signal(full);  
} while (true);
```

- The structure of the *consumer* process

```
Do {
    wait(full);
    wait(mutex);
    ...
    /* remove an item from buffer to next_consumed */
    ...
    signal(mutex);
    signal(empty);
    ...
    /* consume the item in next consumed */
    ...
} while (true);
```

## *Readers-Writers Problem*

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- A data set is shared among a number of concurrent processes
  - Readers – only read the data set; they do **not** perform any updates
  - Writers – can both read and write
- Problem – allow multiple readers to read at the same time
  - Only one single writer can access the shared data at the same time
- Several variations of how readers and writers are considered – all involve some form of priorities
- Shared Data
  - Data set
  - Semaphore `rw_mutex` initialized to 1
  - Semaphore `mutex` initialized to 1
  - Integer `read_count` initialized to 0

- The structure of a *writer* process

```
do {
    wait(rw_mutex);

    ...
    /* writing is performed */
    ...
    signal(rw_mutex);
} while (true);
```

- The structure of a *reader* process

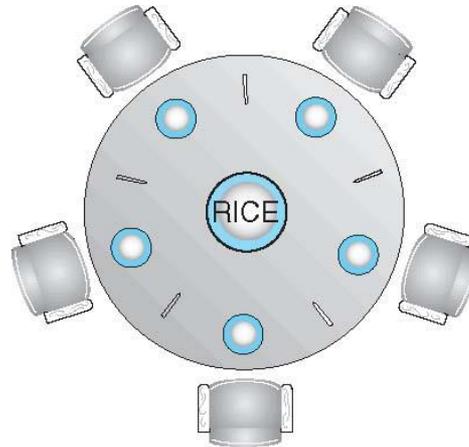
```
do {
    wait(mutex);
    read_count++;
    if (read_count == 1)
        wait(rw_mutex);
    signal(mutex);

    ...
    /* reading is performed */
    ...
    wait(mutex);
    read_count--;
    if (read_count == 0)
        signal(rw_mutex);
    signal(mutex);
} while (true);
```

- ***First*** variation – no reader kept waiting unless writer has permission to use shared object
- ***Second*** variation – once writer is ready, it performs the write ASAP
- Both may have starvation leading to even more variations
- Problem is solved on some systems by kernel providing reader-writer locks

## *Dining-Philosophers Problem*

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- Philosophers spend their lives alternating thinking and eating
- Don't interact with their neighbors, occasionally try to pick up 2 chopsticks (one at a time) to eat from bowl
  - Need both to eat, then release both when done
- In the case of 5 philosophers
  - Shared data
    - Bowl of rice (data set)
    - Semaphore **chopstick [5]** initialized to 1

- The structure of Philosopher  $i$ :

```
do {  
    wait (chopstick[i] );  
    wait (chopstick[ (i + 1) % 5] );  
  
    // eat  
  
    signal (chopstick[i] );  
    signal (chopstick[ (i + 1) % 5] );  
  
    // think  
  
} while (TRUE);
```

- What is the problem with this algorithm?

```
monitor DiningPhilosophers
```

```
{  
    enum { THINKING; HUNGRY, EATING) state [5] ;  
    condition self [5];  
  
    void pickup (int i) {  
        state[i] = HUNGRY;  
        test(i);  
        if (state[i] != EATING) self[i].wait;  
    }  
  
    void putdown (int i) {  
        state[i] = THINKING;  
        // test left and right neighbors  
        test((i + 4) % 5);  
        test((i + 1) % 5);  
    }  
}
```

```
void test (int i) {
    if ((state[(i + 4) % 5] != EATING) &&
        (state[i] == HUNGRY) &&
        (state[(i + 1) % 5] != EATING) ) {
        state[i] = EATING ;
        self[i].signal () ;
    }
}

initialization_code() {
    for (int i = 0; i < 5; i++)
        state[i] = THINKING;
}
}
```

## *Solution to Dining Philosophers (Cont.)*

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- Each philosopher  $i$  invokes the operations `pickup()` and `putdown()` in the following sequence:

*DiningPhilosophers.pickup(i);*

*EAT*

*DiningPhilosophers.putdown(i);*

- No deadlock, but starvation is possible

## *A Monitor to Allocate Single Resource*

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```
monitor ResourceAllocator
{
    boolean busy;
    condition x;
    void acquire(int time) {
        if (busy)
            x.wait(time);
        busy = TRUE;
    }
    void release() {
        busy = FALSE;
        x.signal();
    }
    initialization code() {
        busy = FALSE;
    }
}
```

## *Synchronization Examples*

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- Solaris
- Windows
- Linux
- Pthreads

## *Solaris Synchronization*

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- Implements a variety of locks to support multitasking, multithreading (including real-time threads), and multiprocessing
- Uses **adaptive mutexes** for efficiency when protecting data from short code segments
  - Starts as a standard semaphore spin-lock
  - If lock held, and by a thread running on another CPU, spins
  - If lock held by non-run-state thread, block and sleep waiting for signal of lock being released
- Uses **condition variables**
- Uses **readers-writers** locks when longer sections of code need access to data
- Uses **turnstiles** to order the list of threads waiting to acquire either an adaptive mutex or reader-writer lock
  - Turnstiles are per-lock-holding-thread, not per-object
- Priority-inheritance per-turnstile gives the running thread the highest of the priorities of the threads in its turnstile

- Uses interrupt masks to protect access to global resources on uniprocessor systems
- Uses **spinlocks** on multiprocessor systems
  - Spinlocking-thread will never be preempted
- Also provides **dispatcher objects** user-land which may act mutexes, semaphores, events, and timers
  - **Events**
    - An event acts much like a condition variable
  - Timers notify one or more thread when time expired
  - Dispatcher objects either **signaled-state** (object available) or **non-signaled state** (thread will block)

- Linux:
  - Prior to kernel Version 2.6, disables interrupts to implement short critical sections
  - Version 2.6 and later, fully preemptive
- Linux provides:
  - Semaphores
  - atomic integers
  - spinlocks
  - reader-writer versions of both
- On single-cpu system, spinlocks replaced by enabling and disabling kernel preemption

- Pthreads API is OS-independent
- It provides:
  - mutex locks
  - condition variable
- Non-portable extensions include:
  - read-write locks
  - spinlocks

- Transactional Memory
- OpenMP
- Functional Programming Languages

## *Transactional Memory*

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- A **memory transaction** is a sequence of read-write operations to memory that are performed atomically

```
void update () {  
  
    /* read/write memory */  
  
}
```

## *OpenMP*

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- OpenMP is a set of compiler directives and API that support parallel programming.

```
void update(int value)
{
    #pragma omp critical
    {
        count += value
    }
}
```

The code contained within the `#pragma omp critical` directive is treated as a critical section and performed atomically

## *Functional Programming Languages*

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- Functional programming languages offer a different paradigm than procedural languages in that they do not maintain state
- Variables are treated as immutable and cannot change state once they have been assigned a value
- There is increasing interest in functional languages such as Erlang and Scala for their approach in handling data races