

Programming Languages:

Lecture 12

Chapter 10: Implementing Subprograms

Jinwoo Kim

jwkim@jjay.cuny.edu

- The General Semantics of Calls and Returns
- Implementing “Simple” Subprograms
- Implementing Subprograms with Stack-Dynamic Local Variables
- Nested Subprograms
- Blocks
- Implementing Dynamic Scoping

The General Semantics of Calls and Returns

- The subprogram call and return operations of a language are together called its *subprogram linkage*
- A subprogram call has numerous actions associated with it
 - Implement parameter passing
 - Storage arrangement for local variables
 - Save execution status of calling program
 - Transfer of control
 - Necessary action if nested subprograms supported

- Basic assumption of “Simple” subprogram
 - No nested subprograms
 - All local variables are static
- Save the execution status of the caller
- Carry out the parameter-passing process
- Pass the return address to the callee
- Transfer control to the callee

- If pass-by-value-result parameters are used, move the current values of those parameters to their corresponding actual parameters
- If it is a function, move the functional value to a place the caller can get it
- Restore the execution status of the caller
- Transfer control back to the caller

- Status information about the caller
- Parameters
- Return address
- Return value for functions

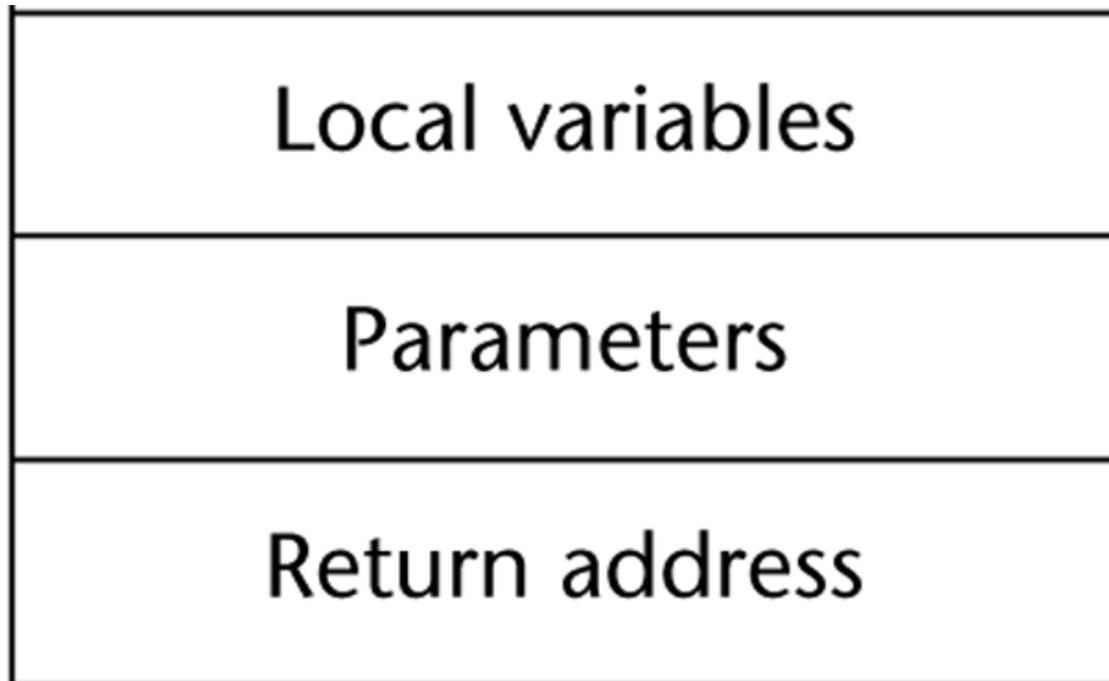
Implementing “Simple” Subprograms: Parts

- Two separate parts of the simple subprogram
 - Actual code part
 - **Constant**
 - Noncode part
 - **local variables and data that can change**
 - They are fixed in size
- The format, or layout, of the noncode part of an executing subprogram is called an *activation record*
 - The data it describes are relevant only during activation
- An *activation record instance* is a concrete example of an activation record
 - The collection of data for a particular subprogram activation

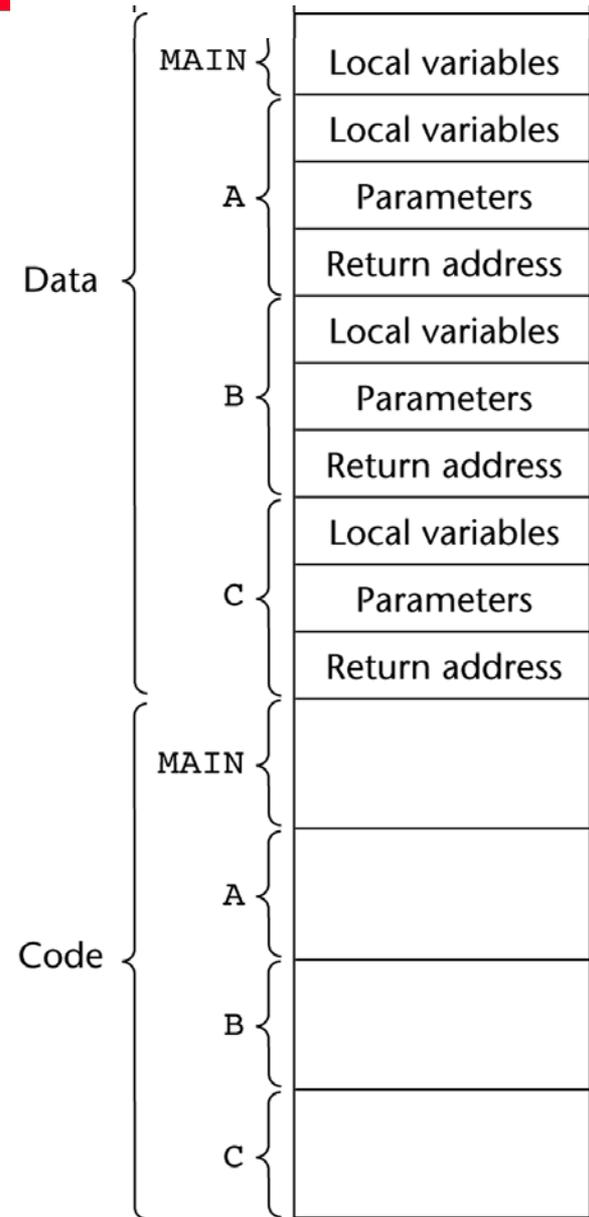
An Activation Record for “Simple” Subprograms

Since simple subprograms do not support recursion, there can be only one active version of a given subprogram at a time

Single instance of activation record for a subprogram exists

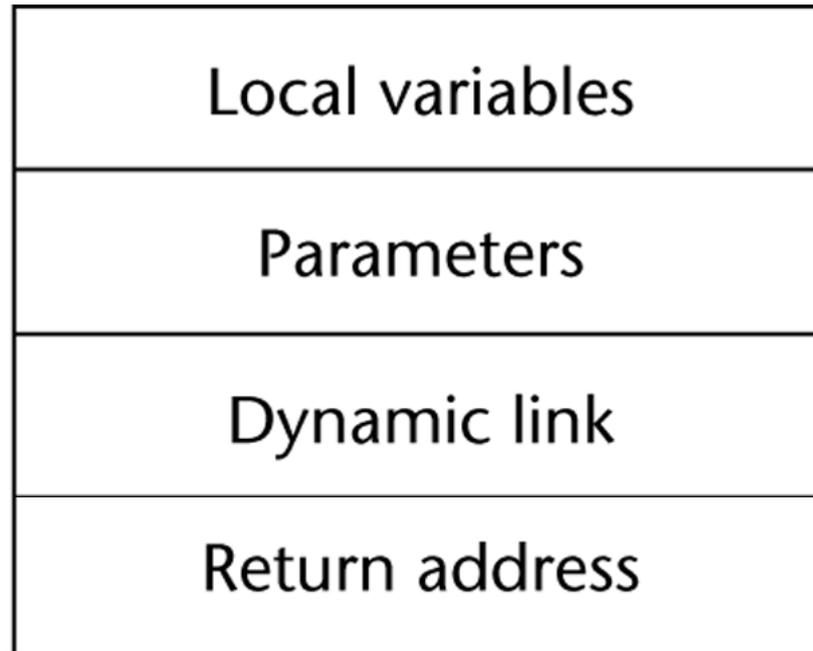


Code and Activation Records of a Program with "Simple" Subprograms



- More complex activation record
 - The compiler must generate code to cause implicit allocation and de-allocation of local variables
 - Recursion must be supported (adds the possibility of multiple simultaneous activations of a subprogram)

Typical Activation Record for a Language with Stack-Dynamic Local Variables



↑
Stack top

- The activation record format is static, but its size may be dynamic
- The *dynamic link* points to the top of an instance of the activation record of the caller
- An activation record instance is dynamically created when a subprogram is called
- Run-time stack

An Example: C Function

```
void sub(float total, int part)
{
    int list[4];
    float sum;
    ...
}
```

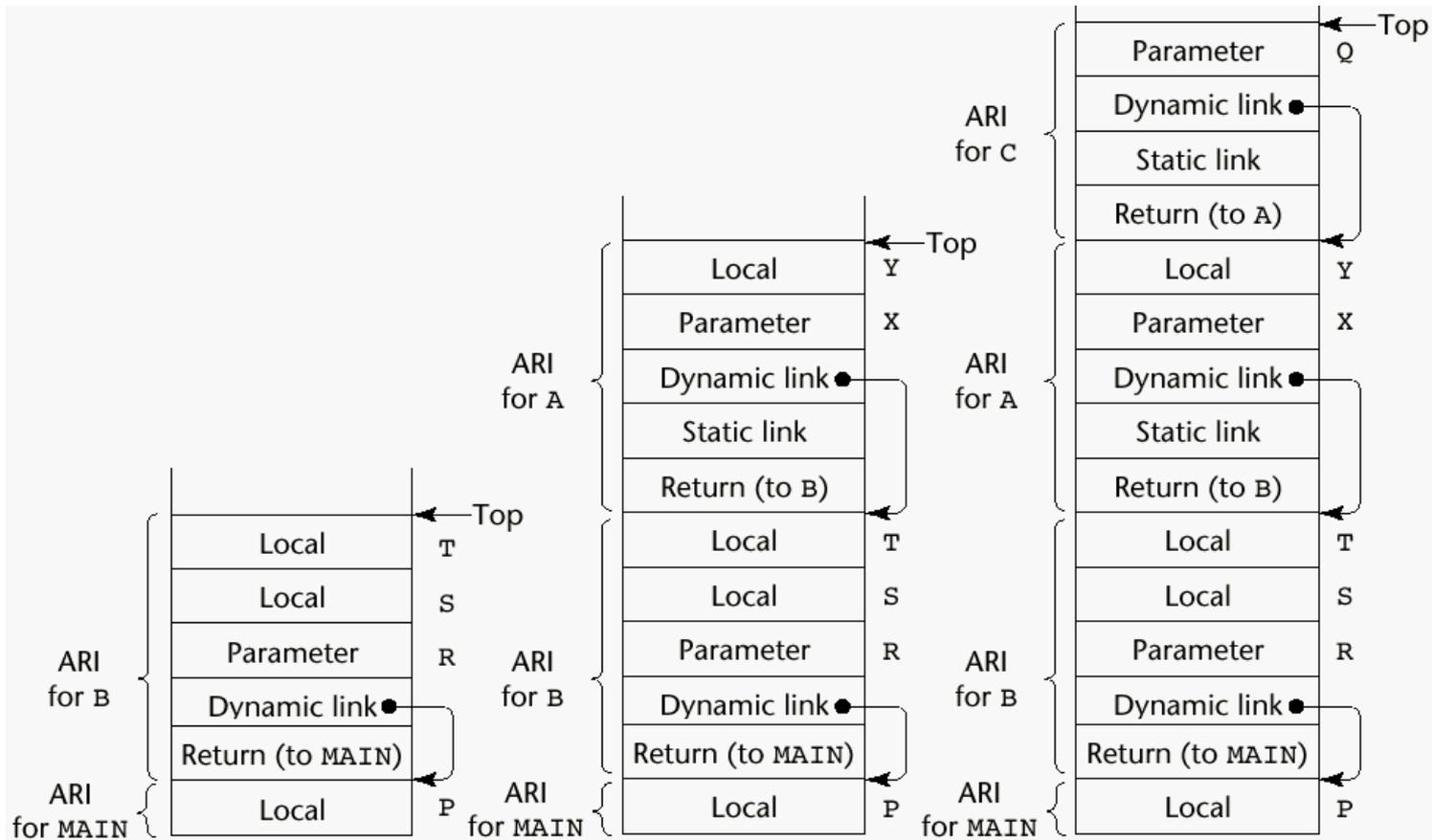
Local	sum
Local	list [4]
Local	list [3]
Local	list [2]
Local	list [1]
Local	list [0]
Parameter	part
Parameter	total
Dynamic link	
Return address	

An Example Without Recursion

```
void A(int x) {
    int y;
    ...
    C(y);
    ...
}
void B(float r) {
    int s, t;
    ...
    A(s);
    ...
}
void C(int q) {
    ...
}
void main() {
    float p;
    ...
    B(p);
    ...
}
```

main calls B
B calls A
A calls C

An Example Without Recursion



ARI = activation record instance

Dynamic Chain and Local Offset

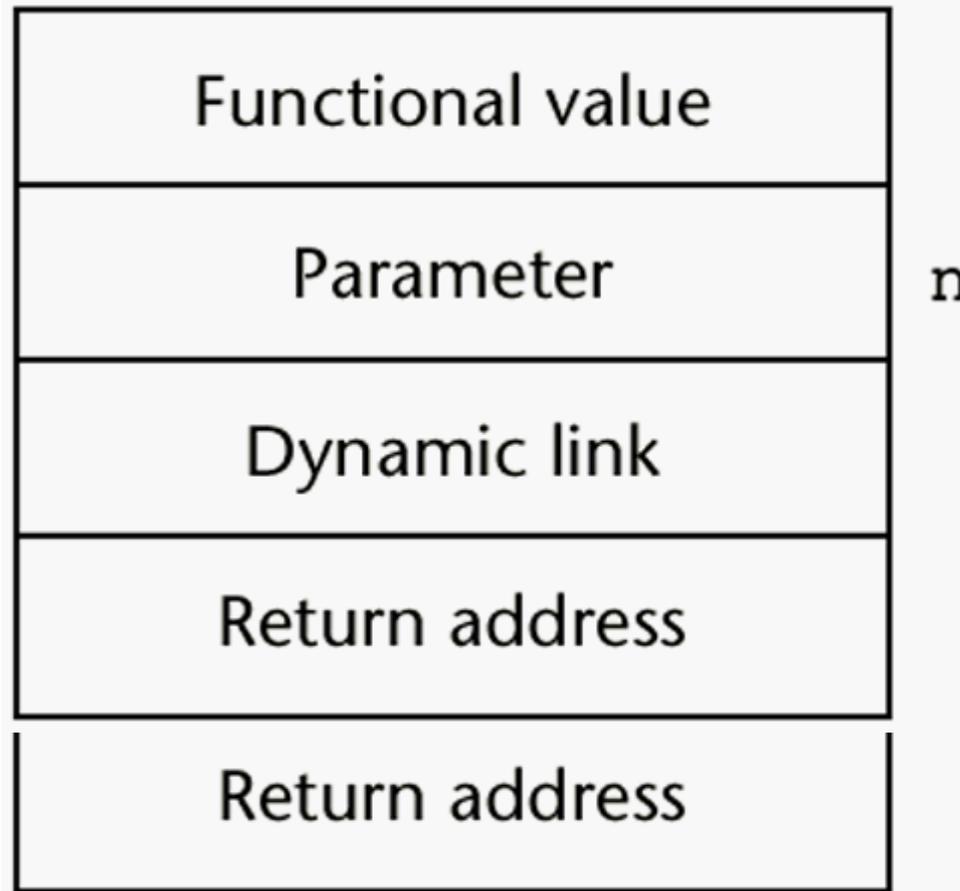
- The collection of dynamic links in the stack at a given time is called the *dynamic chain*, or *call chain*
- Local variables can be accessed by their offset from the beginning of the activation record
 - This offset is called the *local_offset*
- The `local_offset` of a local variable can be determined by the compiler at compile time

An Example With Recursion

- The activation record used in the previous example supports recursion, e.g.

```
int factorial (int n) {  
    <-----1  
    if (n <= 1) return 1;  
    else return (n * factorial(n - 1));  
    <-----2  
}  
  
void main() {  
    int value;  
    value = factorial(3);  
    <-----3  
}
```

Activation Record for factorial



Nested Subprograms

- Some non-C-based static-scoped languages (e.g., Fortran 95, Ada, JavaScript) use stack-dynamic local variables and allow subprograms to be nested
- All variables that can be non-locally accessed reside in some activation record instance in the stack
- The process of locating a non-local reference:
 1. Find the correct activation record instance
 2. Determine the correct offset within that activation record instance

Locating a Non-local Reference

- Finding the offset is easy
- Finding the correct activation record instance
 - Static semantic rules guarantee that all non-local variables that can be referenced have been allocated in some activation record instance that is on the stack when the reference is made

- A *static chain* is a chain of static links that connects certain activation record instances
- The **static link** in an activation record instance for subprogram A points to one of the activation record instances of A's static parent
- The static chain from an activation record instance connects it to all of its static ancestors

Example Pascal Program

```
program MAIN_2;
  var X : integer;
  procedure BIGSUB;
    var A, B, C : integer;
    procedure SUB1;
      var A, D : integer;
      begin { SUB1 }
        A := B + C; <-----1
      end; { SUB1 }
    procedure SUB2(X : integer);
      var B, E : integer;
      procedure SUB3;
        var C, E : integer;
        begin { SUB3 }
          SUB1;
          E := B + A: <-----2
        end; { SUB3 }
      begin { SUB2 }
        SUB3;
        A := D + E; <-----3
      end; { SUB2 }
    begin { BIGSUB }
      SUB2(7);
    end; { BIGSUB }
  begin
    BIGSUB;
  end; { MAIN_2 }
```

Example Pascal Program (continued)

- Call sequence for MAIN_2

MAIN_2 **calls** BIGSUB

BIGSUB **calls** SUB2

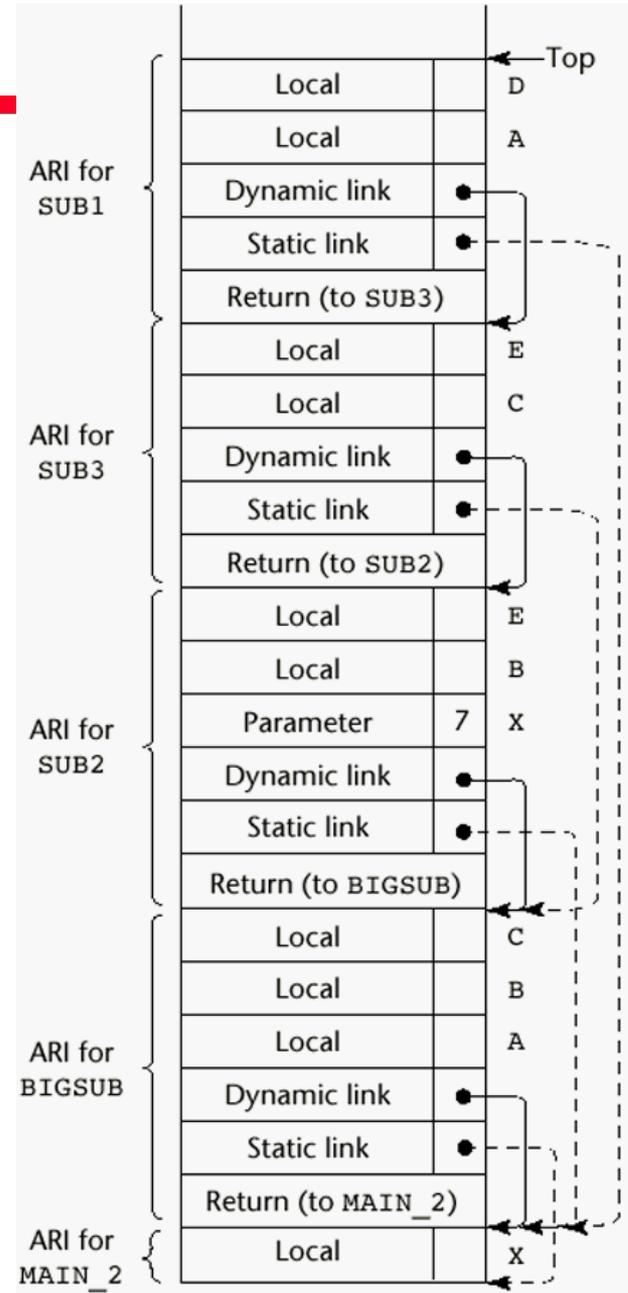
SUB2 **calls** SUB3

SUB3 **calls** SUB1

Stack Contents at Position 1

```

program MAIN_2;
  var X : integer;
  procedure BIGSUB;
    var A, B, C : integer;
    procedure SUB1;
      var A, D : integer;
      begin { SUB1 }
        A := B + C; <-----1
      end; { SUB1 }
    procedure SUB2(X : integer);
      var B, E : integer;
      procedure SUB3;
        var C, E : integer;
        begin { SUB3 }
          SUB1;
          E := B + A: <-----2
        end; { SUB3 }
      begin { SUB2 }
        SUB3;
        A := D + E; <-----3
      end; { SUB2 }
    begin { BIGSUB }
      SUB2(7);
    end; { BIGSUB }
begin
  BIGSUB;
end; { MAIN_2 }
  
```



- An alternative to static chains
- Static links are stored in a single array called a display
- The contents of the display at any given time is a list of addresses of the accessible activation record instances

- Blocks are user-specified local scopes for variables
- An example in C

```
{int temp;  
  temp = list [upper];  
  list [upper] = list [lower];  
  list [lower] = temp  
}
```
- The lifetime of `temp` in the above example begins when control enters the block
- An advantage of using a local variable like `temp` is that it cannot interfere with any other variable with the same name

Implementing Blocks

- Two Methods:
 1. Treat blocks as parameter-less subprograms that are always called from the same location
 - Every block has an activation record; an instance is created every time the block is executed
 2. Since the maximum storage required for a block can be statically determined, this amount of space can be allocated after the local variables in the activation record

Implementing Dynamic Scoping

- *Deep Access*: non-local references are found by searching the activation record instances on the dynamic chain
- *Shallow Access*: put locals in a central place
 - One stack for each variable name
 - Central table with an entry for each variable name

Using Shallow Access to Implement Dynamic Scoping

	A			B
	A	C		A
MAIN_6	MAIN_6	B	C	A
u	v	x	z	w

(The names in the stack cells indicate the program units of the variable declaration.)

Summary

- Subprogram linkage semantics requires many action by the implementation
- Simple subprograms have relatively basic actions
- Stack-dynamic languages are more complex
- Subprograms with stack-dynamic local variables and nested subprograms have two components
 - actual code
 - activation record

Summary (continued)

- Activation record instances contain formal parameters and local variables among other things
- Static chains are the primary method of implementing accesses to non-local variables in static-scoped languages with nested subprograms
- Access to non-local variables in dynamic-scoped languages can be implemented by use of the dynamic chain or thru some central variable table method

Homework #7

- Problem Solving (P. 477 of class textbook)
 - 1, 3, 7, 8, 9
- Due date: One week from assigned date
 - Please hand in printed (typed) form
 - **I do not accept any handwritten assignment**
 - **Exception: pictures**