

# **Programming Languages:**

## **Lecture 5**

### **Chapter 5: Names, Bindings, Type Checking, and Scopes**

**Jinwoo Kim**

**[jwkim@jjay.cuny.edu](mailto:jwkim@jjay.cuny.edu)**

- Introduction
- Names
- Variables
- The Concept of Binding
- Type Checking
- Strong Typing
- Type Compatibility
- Scope and Lifetime
- Referencing Environments
- Named Constants

## *Introduction*

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- Imperative languages are abstractions of von Neumann architecture
  - Memory
  - Processor
- Variables characterized by attributes
  - Type: to design, must consider scope, lifetime, type checking, initialization, and type compatibility

- Design issues for names:
  - Maximum length?
  - Are connector characters allowed?
  - Are names case sensitive?
  - Are special words reserved words or keywords?

## *Names (continued)*

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- Length
  - If too short, they cannot be connotative
  - Language examples:
    - FORTRAN I: maximum 6
    - COBOL: maximum 30
    - FORTRAN 90 and ANSI C: maximum 31
    - Ada and Java: no limit, and all are significant
    - C++: no limit, but implementers often impose one

## *Names (continued)*

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- Connectors
  - Pascal, Modula-2, and FORTRAN 77 don't allow
  - Others do

- Case sensitivity
  - Disadvantage: readability (names that look alike are different)
    - worse in C++ and Java because predefined names are mixed case (e.g. `IndexOutOfBoundsException`)
  - C, C++, and Java names are case sensitive
    - The names in other languages are not

## *Names (continued)*

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- Special words
  - An aid to readability; used to delimit or separate statement clauses
    - A **keyword** is a word that is special only in certain contexts, e.g., in Fortran
      - `Real VarName` (*Real is a data type followed with a name, therefore Real is a keyword*)
      - `Real = 3.4` (*Real is a variable*)
  - A *reserved word* is a special word that cannot be used as a user-defined name



- A variable is an abstraction of a memory cell
- Variables can be characterized as a six-tuple of attributes:
  - Name
  - Address
  - Value
  - Type
  - Lifetime
  - Scope

## *Variables Attributes*

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- Name - not all variables have them
- Address - the memory address with which it is associated
  - A variable may have different addresses at different times during execution
  - A variable may have different addresses at different places in a program
  - If two variable names can be used to access the same memory location, they are called **aliases**
  - Aliases are created via pointers, reference variables, C and C++ unions
  - Aliases are harmful to readability (program readers must remember all of them)

## *Variables Attributes (continued)*

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- *Type* - determines the range of values of variables and the set of operations that are defined for values of that type; in the case of floating point, type also determines the precision
- *Value* - the contents of the location with which the variable is associated
- *Abstract memory cell* - the physical cell or collection of cells associated with a variable

## *The Concept of Binding*

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- The l-value of a variable is its address
- The r-value of a variable is its value
- A *binding* is an association, such as between an attribute and an entity, or between an operation and a symbol
- *Binding time* is the time at which a binding takes place.

## *Possible Binding Times*

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- Language design time -- bind operator symbols to operations
- Language implementation time-- bind floating point type to a representation
- Compile time -- bind a variable to a type in C or Java
- Load time -- bind a FORTRAN 77 variable to a memory cell (or a C `static` variable)
- Runtime -- bind a nonstatic local variable to a memory cell

## *Static and Dynamic Binding*

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- A binding is *static* if it first occurs before run time and remains unchanged throughout program execution
- A binding is *dynamic* if it first occurs during execution or can change during execution of the program

- How is a type specified?
- When does the binding take place?
- If static, the type may be specified by either an explicit or an implicit declaration

## *Explicit/Implicit Declaration*

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- An *explicit declaration* is a program statement used for declaring the types of variables
- An *implicit declaration* is a default mechanism for specifying types of variables (the first appearance of the variable in the program)
- FORTRAN, PL/I, BASIC, and Perl provide implicit declarations
  - Advantage: writability
  - Disadvantage: reliability (less trouble with Perl)



## *Dynamic Type Binding*

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- Dynamic Type Binding (JavaScript and PHP)
- Specified through an assignment statement  
e.g., JavaScript

```
list = [2, 4.33, 6, 8];  
list = 17.3;
```

  - Advantage: flexibility (generic program units)
  - Disadvantages:
    - High cost (dynamic type checking and interpretation)
    - Type error detection by the compiler is difficult

## *Variable Attributes (continued)*

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- Type Inferencing (ML, Miranda, and Haskell)
  - Rather than by assignment statement, types are determined from the context of the reference
- Storage Bindings & Lifetime
  - Allocation - getting a cell from some pool of available cells
  - Deallocation - putting a cell back into the pool
- The lifetime of a variable is the time during which it is bound to a particular memory cell

## *Categories of Variables by Lifetimes*

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- Static--bound to memory cells before execution begins and remains bound to the same memory cell throughout execution, e.g., all FORTRAN 77 variables, C static variables
  - Advantages: efficiency (direct addressing), history-sensitive subprogram support
  - Disadvantage: lack of flexibility (no recursion)

## *Categories of Variables by Lifetimes*

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- Stack-dynamic--Storage bindings are created for variables when their declaration statements are elaborated
- If scalar, all attributes except address are statically bound
  - local variables in C subprograms and Java methods
- Advantage: allows recursion; conserves storage
- Disadvantages:
  - Overhead of allocation and deallocation
  - Subprograms cannot be history sensitive
  - Inefficient references (indirect addressing)

## *Categories of Variables by Lifetimes*

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- *Explicit heap-dynamic* -- Allocated and deallocated by explicit directives, specified by the programmer, which take effect during execution
- Referenced only through pointers or references, e.g. dynamic objects in C++ (via new and delete), all objects in Java
- Advantage: provides for dynamic storage management
- Disadvantage: inefficient and unreliable

## *Categories of Variables by Lifetimes*

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- *Implicit heap-dynamic*--Allocation and deallocation caused by assignment statements
  - all variables in APL; all strings and arrays in Perl and JavaScript
- Advantage: flexibility
- Disadvantages:
  - Inefficient, because all attributes are dynamic
  - Loss of error detection

## *Type Checking*

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- Generalize the concept of operands and operators to include subprograms and assignments
- *Type checking* is the activity of ensuring that the operands of an operator are of compatible types
- A *compatible type* is one that is either legal for the operator, or is allowed under language rules to be implicitly converted, by compiler-generated code, to a legal type
  - This automatic conversion is called a coercion
- A *type error* is the application of an operator to an operand of an inappropriate type

## *Type Checking (continued)*

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- If all type bindings are static, nearly all type checking can be static
- If type bindings are dynamic, type checking must be dynamic
- A programming language is *strongly typed* if type errors are always detected



- Advantage of strong typing: allows the detection of the misuses of variables that result in type errors
- Language examples:
  - FORTRAN 77 is not: parameters, EQUIVALENCE
  - Pascal is not: variant records
  - C and C++ are not: parameter type checking can be avoided; unions are not type checked
  - Ada is, almost (UNCHECKED CONVERSION is loophole)  
(Java is similar)

## *Strong Typing (continued)*

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- Coercion rules strongly affect strong typing--they can weaken it considerably (C++ versus Ada)
- Although Java has just half the assignment coercions of C++, its strong typing is still far less effective than that of Ada

## *Name Type Compatibility*

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- *Name type compatibility* means the two variables have compatible types if they are in either the same declaration or in declarations that use the same type name
- Easy to implement but highly restrictive:
  - Subranges of integer types are not compatible with integer types
  - Formal parameters must be the same type as their corresponding actual parameters (Pascal)

## *Structure Type Compatibility*

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- *Structure type compatibility* means that two variables have compatible types if their types have identical structures
- More flexible, but harder to implement

## *Type Compatibility (continued)*

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- Consider the problem of two structured types:
  - Are two record types compatible if they are structurally the same but use different field names?
  - Are two array types compatible if they are the same except that the subscripts are different?  
(e.g. [1..10] and [0..9])
  - Are two enumeration types compatible if their components are spelled differently?
  - With structural type compatibility, you cannot differentiate between types of the same structure (e.g. different units of speed, both float)

## *Variable Attributes: Scope*

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- The *scope* of a variable is the range of statements over which it is visible
- The *nonlocal variables* of a program unit are those that are visible but not declared there
- The scope rules of a language determine how references to names are associated with variables

## *Static Scope*

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- Based on program text
- To connect a name reference to a variable, you (or the compiler) must find the declaration
- Search process: search declarations, first locally, then in increasingly larger enclosing scopes, until one is found for the given name
- Enclosing static scopes (to a specific scope) are called its static ancestors; the nearest static ancestor is called a static parent

## *Scope (continued)*

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- Variables can be hidden from a unit by having a "closer" variable with the same name
- C++ and Ada allow access to these "hidden" variables
  - In Ada: `unit.name`
  - In C++: `class_name::name`



## *Blocks*

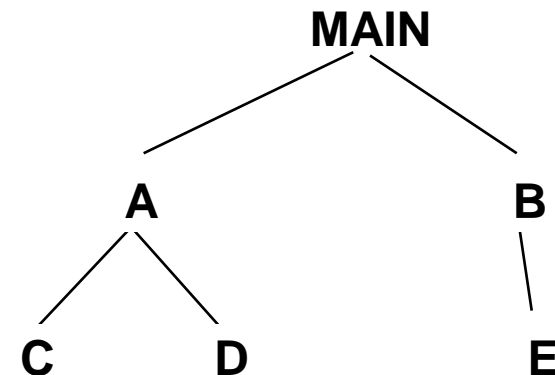
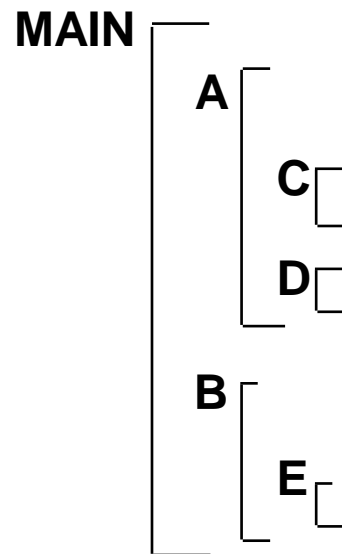
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- A method of creating static scopes inside program units-- from ALGOL 60
- Examples:

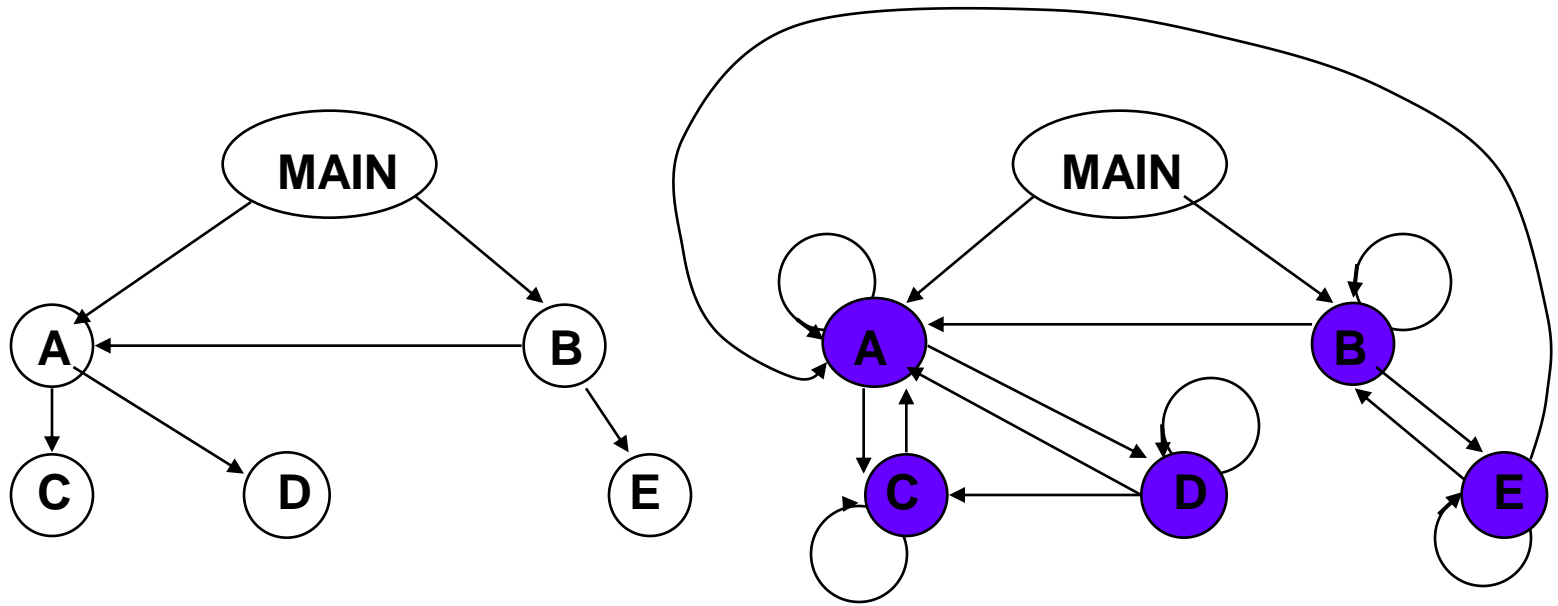
C and C++: `for (...) {`  
                    `int index;`  
                    `...`  
                    `}`

Ada: `declare LCL : FLOAT;`  
      `begin`  
          `...`  
      `end`

- Assume MAIN calls A and B  
A calls C and D  
B calls A and E



## Static Scope Example



## *Static Scope (continued)*

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- Suppose the spec is changed so that D must now access some data in B
- Solutions:
  - Put D in B (but then C can no longer call it and D cannot access A's variables)
  - Move the data from B that D needs to MAIN (but then all procedures can access them)
- Same problem for procedure access
- Overall: static scoping often encourages many globals

- Based on calling sequences of program units, not their textual layout (temporal versus spatial)
- References to variables are connected to declarations by searching back through the chain of subprogram calls that forced execution to this point

**MAIN**

```
- declaration of x
  SUB1
    - declaration of x -
    ...
    call SUB2
    ...
  SUB2
    ...
    - reference to x -
    ...
  ...
  call SUB1
  ...
```

MAIN calls SUB1  
SUB1 calls SUB2  
SUB2 uses x

## *Scope Example*

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- Static scoping
  - Reference to x is to MAIN's x
- Dynamic scoping
  - Reference to x is to SUB1's x
- Evaluation of Dynamic Scoping:
  - Advantage: convenience
  - Disadvantage: poor readability

## Scope Example 1 (Perl)

- my vs local
  - my marks a variable as private in a lexical scope
  - local marks a variable as private in a dynamic scope

```
$x = 1;  
sub foo { print "$x\n"; }  
sub bar { local $x; $x = 2; foo(); }
```

```
&foo; # prints ???
```

```
&bar; # prints ???
```

```
&foo; # prints ???
```



## *Scope Example 2 (Perl)*

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```
$var = 5;  
print $var, "\n";  
&fun1;  
print $var, "\n";  
  
# subroutines  
sub fun1 {  
    local $var = 10;  
    print $var, "\n";  
    &fun2; # calling subroutine fun2  
    print $var, "\n";  
}  
  
sub fun2 { $var ++; }
```

## *Scope and Lifetime*

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- Scope and lifetime are sometimes closely related, but are different concepts
- Consider a `static` variable in a C or C++ function

## *Referencing Environments*

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- The *referencing environment* of a statement is the collection of all names that are visible in the statement
- In a static-scoped language, it is the local variables plus all of the visible variables in all of the enclosing scopes
- In a dynamic-scoped language, the referencing environment is the local variables plus all visible variables in all active subprograms
  - A subprogram is active if its execution has begun but has not yet terminated

## *Named Constants*

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- A *named constant* is a variable that is bound to a value only when it is bound to storage
- Advantages: readability and modifiability
- Used to parameterize programs
- The binding of values to named constants can be either static (called *manifest constants*) or dynamic
- Languages:
  - FORTRAN 90: constant-valued expressions
  - Ada, C++, and Java: expressions of any kind

## *Variable Initialization*

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- The binding of a variable to a value at the time it is bound to storage is called *initialization*
- Initialization is often done on the declaration statement, e.g., in Java

```
int sum = 0;
```

- Case sensitivity and the relationship of names to special words represent design issues of names
- Variables are characterized by the six-tuples: name, address, value, type, lifetime, scope
- Binding is the association of attributes with program entities
- Scalar variables are categorized as: static, stack dynamic, explicit heap dynamic, implicit heap dynamic
- Strong typing means detecting all type errors

## *Homework #3 (part 1)*

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- **Programming Exercise**

Write three functions in C or C++: one that declares a large array statically, one that declares the same large array on the stack, and one that creates the same large array from the heap. Call each of the subprograms a large number of times (at least 100,000) and output the time required by each. Explain the results.

- **Problem Solving (P. 229 of class textbook)**

- 5, 8, 11, 12

- **Due date: One week from assigned date**

- Please hand in printed (typed) form
    - I do not accept any handwritten assignment
    - Exception: pictures